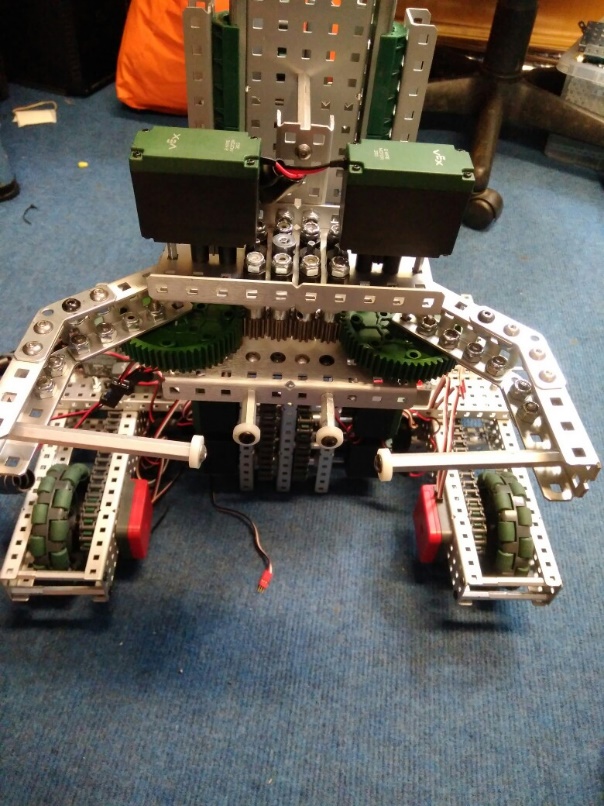
Robot v1.22



**Specification:**

* 6 Motor HS drive
* 2 drive chains
* 4 wheels
* Aluminium structure
* 4 motor lift
* 2 stage lift
* 2 motor claw

**Dimensions:**

17.5” x 15” x 17.5” when not extended

Logged by Robbie Buxton

14/07/2017 – 13:46

**Overview:**

The latest changes we have made is an overhaul to the claw, making the transition to using standoffs as the main method of grip. We found these to be better as they are smaller meaning that the claw is more likely to get into the cone and get a stable grip. We have also added two static standoffs to improve the grip of the claw

**What needs to be changed:**

* Add a third stage
* Wire up shaft encoders

**Changes Made:**

* Improved claw
* Added shaft encoders